

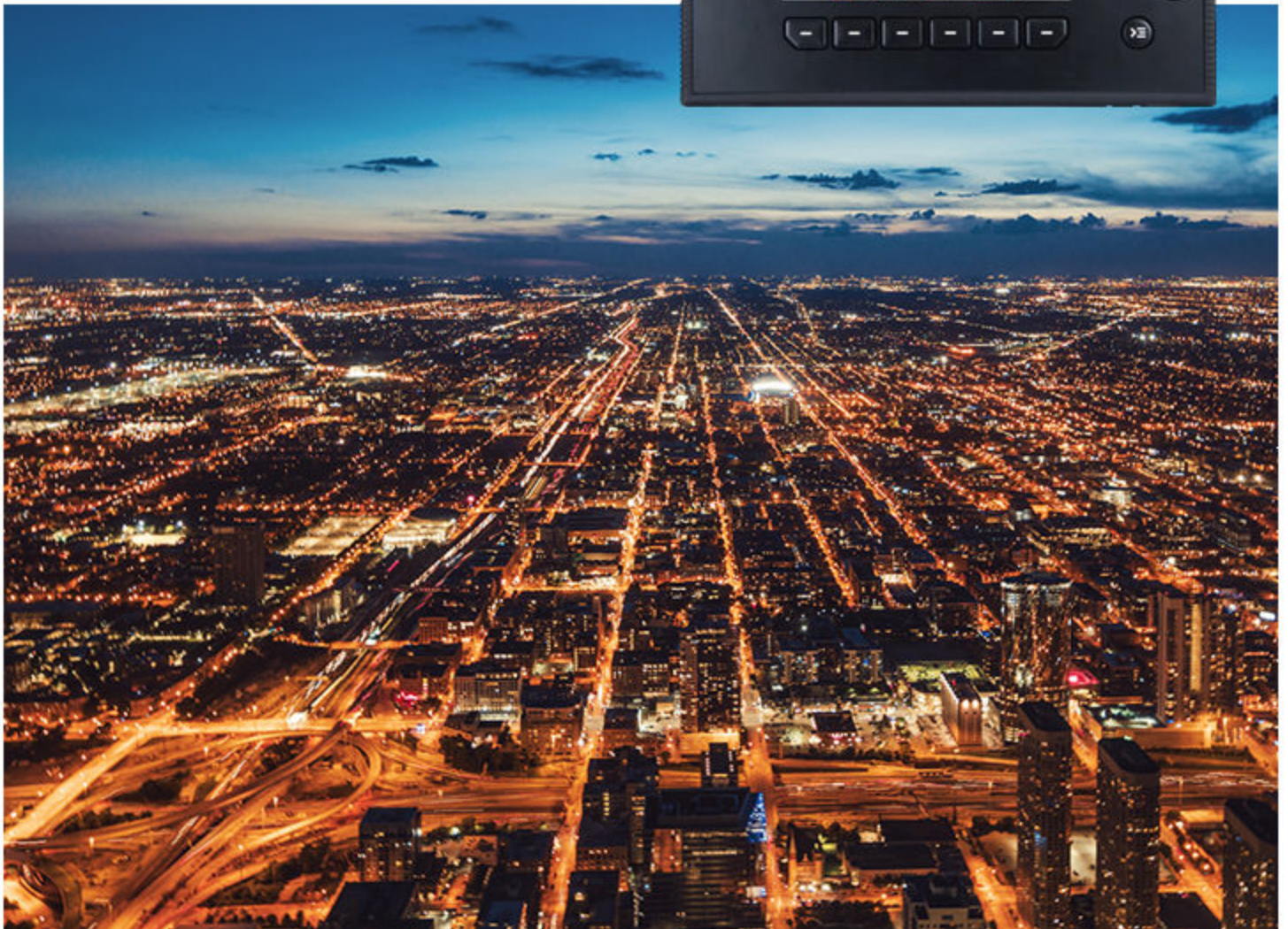
iE 250

intelligent Energy controller

Data sheet



Improve
Tomorrow



1. intelligent Energy controller

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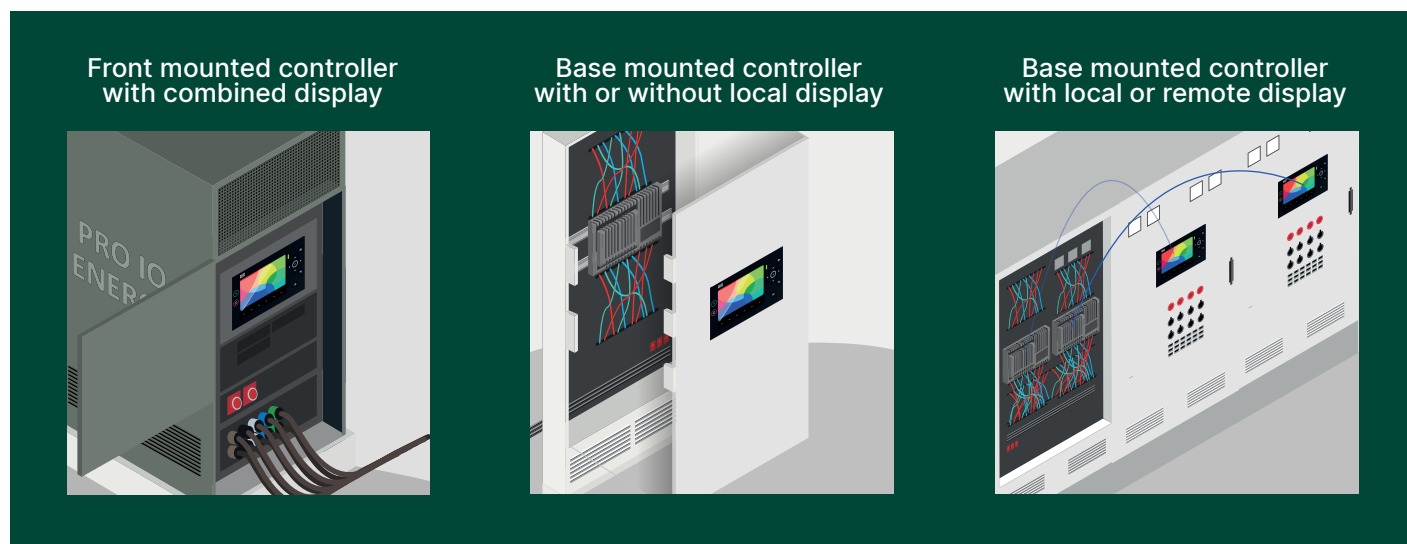
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1. intelligent Energy controller

1.1 About the controller

1.1.1 About the controller types

The iE 250 is a versatile and modular-designed controller for land applications. Its design enables you to tailor the installation to your needs.



An extensive range of control, protection and supervision features. Applications range from generator control and protection to engineered energy management solutions with our market-leading fuel optimisation technology.

Each controller is assigned a type from the factory. You can the type of controller on the Application single-line drawing.

Controller type	Controls and protects
Single genset controller	<ul style="list-style-type: none">• A prime mover, generator, generator breaker, mains connection, and mains breaker• A prime mover, generator, generator breaker, and mains connection• A prime mover, generator, and generator breaker
Generator controller	A prime mover, generator, and generator breaker.
Mains controller	<ul style="list-style-type: none">• A mains connection, and mains breaker.• A mains connection, mains breaker, and a tie breaker.
Bus tie breaker controller	A bus tie breaker.

A power management system can include a number of controllers. The controllers work together to ensure effective power management.

1.1.2 **Need more information?**

Get direct access to the resources that you need by using the links below.



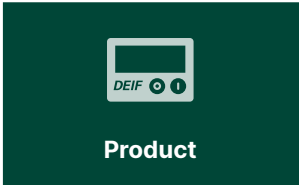
Official DEIF homepage.



See all the related iE 250 documentation.



Self-help resources and how to contact DEIF for assistance.



iE 250 product page.



Download the latest software.



Learn how to use this product.



Help improve our documentation with your feedback.



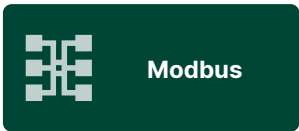
AutoCAD drawing



Step STP drawing



3D PDF drawing *



Modbus tables

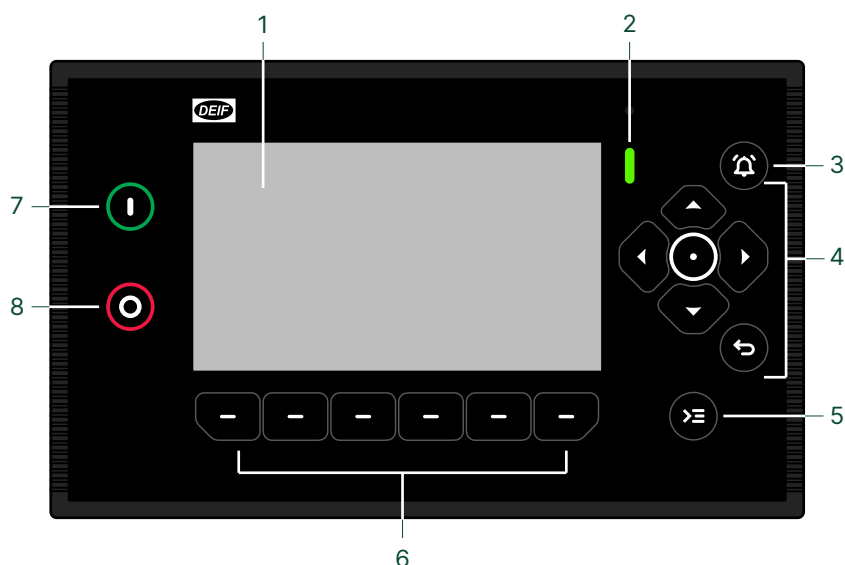
NOTE * To view a 3D PDF you must enable multimedia and 3D content in your PDF viewer.

1.1.3 **Software versions**

The information in this document relates to software versions:

Software	Details	Version
iE 250	Controller application	2.0.1.x
PICUS	PC software	1.0.21.x

1.1.4 Display layout



No.	Item	Notes
1	Display screen	7" colour touch screen.
2	Status LED	Multi-colour LED for status indication.
3	Notification centre button	Silences the alarm horn relay, and opens the Notification centre , which shows alarms and events.
4	Navigation buttons	Up, down, left, and right arrows.
	Enter button	Confirms the selection.
	Back button	<ul style="list-style-type: none"> Returns to the previous page Shows the menu. Hold: Change to Dashboard
5	Control centre button	Opens the Control centre .
6	Configurable buttons	Buttons are can be activated either by pressing the physical button or the soft key on the screen. *
7	Start button	In manual or local operation, it starts the asset. In a Power management system and in AUTO mode, it starts the Power management.
8	Stop button **	In manual or local operation, it stops the asset. In a Power management system and in AUTO mode, it stops the Power management.

NOTE * Dashboard pages can be created, copied and modified, to assign different functions to the buttons (with PICUS and the Display designer).

** Double press to override cooldown process. Press again to cancel **Idle run**, if configured.

1.1.5 Emulation

iE 250 includes an emulation tool to verify and test the functionality of the application, for example plant modes and logic, breaker handling, mains and generator operation.

Application emulation is useful for training, customising plant requirements and for testing basic functionality that needs to be set up or verified.

In a power management system it is possible to control the entire plant, when connected to just one of the controllers.

1.2 Functions and features

1.2.1 General functions and features

Modular and configurable design	
Mounting choices *	Choice of either: <ul style="list-style-type: none"> • Front mounted. • Base mounted. *
Display	Local display * <ul style="list-style-type: none"> • For base mounted. * Remote display * <ul style="list-style-type: none"> • For base or front mounted. *
New design - easy mount	Front mount controller or display has same cut-out footprint as the DEIF AGC 150.
Easy expansion	Add-on modules <ul style="list-style-type: none"> • Measurement Input Output module MIO2.1. Plug-in modules * <ul style="list-style-type: none"> • 8 Digital bi-directional channels. * • 4 Analogue bi-directional channels. * • Analogue load sharing. * Additional input/output possibilities <ul style="list-style-type: none"> • ML 300 series modules. • CIO series modules. *

NOTE * Contact DEIF for availability.

Power management features	
Plant modes	<ul style="list-style-type: none"> • Island mode • Automatic mains failure • Fixed power • Peak shaving • Load take-over • Mains power export
Power management operation	CAN bus based power management: <ul style="list-style-type: none"> • 32 prime movers and generators (gensets)/mains with breakers • 8 bus tie breakers on the generator bus or load bus
Load control	Load control between controllers up to 32 assets. Load control between iE 250 and other DEIF controllers up to 16 gensets. Generator controllers can have equal load sharing. Generator controllers can synchronise/de-load Mains and BTB controllers. External breaker position feedback. * Automatic detection of load sharing busbar sections (including for a ring busbar).
Priority selection	<ul style="list-style-type: none"> • Manual * • Running hours • Fuel optimisation
Additional features	Generator load-dependent start and stop Hybrid ready (Solar and battery) *

Power management features

Asymmetrical generator load sharing
N + X
Safety stop of generator
Flexible application *

NOTE * Contact DEIF for availability.

Application

Single-line application drawing

Flexible applications. *

Busbar

Busbar can have a ring connection.

Breakers

Redundant breaker feedback on bus tie breakers.
Externally controlled breakers. *

NOTE * Contact DEIF for availability.

AC configuration features

Nominal settings

4 sets of settings.

AC configuration

Three-phase
Split-phase L1L2
Split-phase L1L3
Single phase L1

4th current

Measurement for earth or neutral protections, or mains power.

Additional features

- 100 to 690 V AC (selectable)
- CT -/1 or -/5 (selectable)

General functions

Regulation

Governor:

- Active power load sharing
- Fixed frequency
- Fixed active power
- Frequency droop
- Fixed RPM

AVR:

- Reactive power load sharing
- Fixed voltage
- Fixed reactive power
- Fixed cos phi
- Voltage droop

General purpose PID regulators
Three sets of temperature-dependent power derate settings.
Set point selection using digital input, Modbus, and/or CustomLogic or CODESYS.

Pre-programmed sequences

Generator: *

Generator start and stop.

Breaker:

General functions	
	Breaker open sequence (with and without de-loading). Breaker close sequence (with synchronisation).
Synchronisation	Automatic synchronisation and de-loading. Operator-initiated synchronisation and de-loading possible. Choose between Static or Dynamic synchronisation. De-load before opening.
Breaker control	Breaker types (with configurable parameters): Pulse breaker. Breaker position detection and alarms.
Configurable Idle run **	Protect the engine with additional warm-up or cooldown periods.
Advanced troubleshooting	Controller self-test. Event and alarm log, with real-time clock.
User management	Configurable permission roles and users.
AC measurements	AC measurements can be configured with average filters for use on noisy or oscillating systems for the displayed information. Controller data and calculations are not affected. Actual values are always used for the calculations and protections. Choice of <i>No filters</i> , or <i>average over a selected time</i> (200 or 800 milliseconds).
CPU load overview	<i>Currently, Average over 10 seconds. Average over 1 minute, or Average over 10 minutes.</i>
CODESYS	Option: Extended controller functionality with soft PLC. CODESYS runtime. Custom information pop-up messages and status texts. Provide better customised user experience by delivering messaging and status information from the CODESYS application. View CODESYS license key in web config.
Additional hardware/ software features	Power supply voltage measurement diode offset. Output configuration (function, coil state). Analogue input sensor failure (below and above range). Analogue input pre-configured curves, plus up to 20 customisable curves. Analogue output pre-configured curves, plus up to 20 customisable curves.

NOTE * Generator controllers only.

** Supported engines only.

Display	
Easy and user-friendly interface	Easy control with customisable dashboards. Adaptive mimics. Configurable physical buttons. 7" colour touch screen that can be used in combination with physical buttons.
Fast short-cut button	Configurable shortcut feature gives the user easy access to frequently used functions.

Communication	
Plug and play	Automatic network configuration (uses static IPv6). Automatic date and time synchronisation between all controllers in the system. NTP time synchronisation with NTP servers.
Redundancy	Redundant CAN bus for Power management. Redundant controller support. **
Ethernet communication	<ul style="list-style-type: none"> Secured protocols on Ethernet communication.
CAN bus communication	3 CAN ports for:

Communication	
	<ul style="list-style-type: none"> • Power management. • J1939-based ECU communication. • Communication to CIO modules. ** • Communication to Digital AVR: <ul style="list-style-type: none"> ◦ DVC 350. ◦ DVC 550. ◦ Leroy Somer D550.
RS 485 communication *	2 serial ports configurable as client or server.
Modbus server	Supports multiple Modbus protocols: TCP/IP, RTU. * Standard protocol: Modbus server, TCP/IP.

NOTE * For future use.
 ** Contact DEIF for availability.



More information

See [EIC manual](#) for list of supported J1939 engines and manufacturers.

Configuration tool - PICUS	
General features	PC software to connect to one or more controllers. Application design (Single-line diagram) tool for creation, configuration and broadcast. Updated firmware for the controller and display. Supports multiple controller languages. Backup / restore projects or configurations. Commissioning tools.
Display designer	For creation and configuration on the display: Dashboard layout and widgets. Header design and widgets.
Controller configuration	Configure controller inputs, outputs, and parameters. View status and live data. Manage backups and restores. Use offline projects to view or edit a controller configuration.
System emulation	Safely mimic the environment that the controller connects to (loads, inputs, and failure scenarios).
System supervision	Supervise and control the application.
Alarms and log events	Manage alarms. Run alarm tests. View event logs and J1939 DM2 logs (if ECU enabled).
Input / output status	See an overview for all the input and output values for the controller, extension racks, and ECU (if configured).
Trending	Record and save operational values over a period of time. Export recorded trace values to a .csv file.
TAGs	Show or hide Tags for Alarm pop-up, alarms, log, parameters, and reports.
Permission control	Role and user management.
CustomLogic	User-friendly logic configuration tool, based on ladder logic and function blocks. Selectable input events and output commands per controller. Inter-controller communication with each controller in the system. (For compatible controllers). Modbus signals (inputs and/or outputs).

1.3 Alarms and protections

1.3.1 Alternating current (AC) protections

The controllers include the following alternating current (AC) protections, according to IEEE Std. C37.2™-2008.

The *operate time* is defined in IEC 447-05-05 (from the instant when the need for the protection arises, to when the controller output has responded). For each protection, the *operate time* is given for the minimum user-defined time delay.

All AC alarms are available on all controller types, unless noted in the alarm column.

Controller type	A-side	B-side
SINGLE genset	Generator	Mains
GENSET	Generator	Busbar
MAINS	Mains	Busbar
BUS TIE breaker	Busbar A	Busbar B

AC protections for the A-side

Protection	IEC symbol (IEC 60617)	ANSI (IEEE C37.2)	Operate time	Based on	Alarms
Over-voltage	U>	59	< 100 ms	The highest phase-to-phase (or phase-to-neutral) voltage	2
Under-voltage	U<	27	< 100 ms	The lowest phase-to-phase (or phase-to-neutral) voltage	3
Voltage unbalance (voltage asymmetry)	UUB>	47	< 200 ms *	The highest difference between any of the 3 phase-to-phase (or phase-to-neutral) voltage true RMS values, and the average value	1
Positive sequence under-voltage	U ₁ <	27D	< 60 ms ***	The estimated phase-to-neutral voltage phasors	1
Negative sequence voltage	U ₂ >	47	< 200 ms *	The estimated phase-to-neutral voltage phasors	1
Zero sequence voltage	U ₀	59U ₀	< 200 ms *	The estimated phase-to-neutral voltage phasors	1
Over-current	3I>	50TD	< 100 ms	The highest phase current true RMS value	4
Fast over-current (short circuit)	3I>>>	50/50TD	< 50 ms	The highest phase current true RMS value	2
Current unbalance (average)	IUB>	46	< 200 ms *	The highest difference between any of the 3 phase currents and the average value	1
Current unbalance (nominal)	IUB>	46	< 200 ms *	The highest difference between any of the 3 phase currents and the nominal value	1
Directional over-current	I> →	67	< 100 ms	The highest phase current true RMS value, with the direction from the active power	2 **
Inverse time over-current	It>	51	-	The highest phase current true RMS value, based on IEC 60255 part 151	1

Protection	IEC symbol (IEC 60617)	ANSI (IEEE C37.2)	Operate time	Based on	Alarms
Negative sequence current	$I_2 >$	46	< 200 ms *	The estimated current phasors	1
Zero sequence current	$I_0 >$	51 I_0	< 200 ms *	The estimated current phasors	1
Over-frequency	$f >$	81O	< 100 ms	The lowest fundamental frequency of a phase voltage	2
Under-frequency	$f <$	81U	< 100 ms	The highest fundamental frequency of a phase voltage	3
Overload (power export)	$P >$	32	< 100 ms	The active power (all phases)	5
Reverse power (power import)	$P <$	32R	< 100 ms	The active power (all phases)	2
Over-excitation (reactive power export)	$Q >$	40O	< 100 ms	The reactive power (all phases)	2
Under-excitation (reactive power import/ loss of excitation)	$Q <$	40U	< 100 ms	The reactive power (all phases)	2
Active synchroniser (including blackout close)	-	25A	-	The frequency difference, the voltage difference, and the phase across the breaker	Not an alarm

NOTE * These operate times include the minimum user-defined delay of 100 ms.

** The **BUS TIE breaker** controller has 4 directional-over current alarms.

*** This operate time includes the minimum user-defined delay of 20 ms.

AC protections for the B-side

Protection	IEC symbol (IEC 60617)	ANSI (IEEE C37.2)	Operate time	Based on	Alarms
Over-voltage	$U >$	59	< 50 ms	The highest phase-to-phase (or phase-to-neutral) voltage	3
Under-voltage	$U <$	27	< 50 ms	The lowest phase-to-phase (or phase-to-neutral) voltage	4
Voltage unbalance (voltage asymmetry)	$UUB >$	47	< 200 ms *	The highest difference between any of the 3 phase-to-phase (or phase-to-neutral) voltage true RMS values, and the average value	1
Positive sequence under-voltage	$U_1 <$	27D	< 60 ms **	The estimated phase-to-neutral voltage phasors	1
Negative sequence voltage	$U_2 >$	47	< 200 ms *	The estimated phase-to-neutral voltage phasors	1
Zero sequence voltage	U_0	59 U_0	< 200 ms *	The estimated phase-to-neutral voltage phasors	1
Over-frequency	$f >$	81O	< 50 ms	The lowest fundamental frequency of a phase voltage	3
Under-frequency	$f <$	81U	< 50 ms	The highest fundamental frequency of a phase voltage	4

NOTE * This operate time includes the minimum user-defined delay of 100 ms.

** This operate time includes the minimum user-defined delay of 20 ms.

AC protections for the A-side or the B-side *

Protection	IEC symbol (IEC 60617)	ANSI (IEEE C37.2)	Operate time	Based on	Alarms
Vector shift	$d\varphi/dt$	78	< 40 ms	Individual phase mode: A phase shows vector shift. All phases mode: All phases show vector shift.	1
ROCOF (df/dt)	df/dt	81R	< 200 ms (12 half periods)	The rate of change of the fundamental frequency of the 3 phase voltage system.	1
V< and Q<	U< Q<	27Q	< 250 ms	The highest phase-to-phase (or phase-to-neutral) voltage; the reactive power (all phases) and the highest phase current true RMS value.	2
Average over-voltage	-	59AVG	-	The RMS phase-to-phase (or phase-to-neutral) voltage, averaged over a minimum of 30 s (configurable).	2

NOTE * These protections can be configured for either the A-side or the B-side.

Other AC protections for the A-side

Protection	IEC symbol (IEC 60617)	ANSI (IEEE C37.2)	Operate time	Based on	Alarms
Earth inverse time over-current		51G	-	The current RMS value, measured by the 4th current measurement, filtered to attenuate the third harmonic (at least 18 dB).	1 *
Neutral inverse time over-current		51N	-	The current RMS value, measured by the 4th current measurement.	1 *

NOTE * These protections each need the 4th current measurement. You can therefore only use one of these protections.

Other features

Feature	IEC symbol (IEC 60617)	ANSI (IEEE C37.2)	Operate time	Based on
Lockout relay		86	-	Protected equipment. Alarms can be configured with a Latch, which remain active until the operator resets the latch.

1.4 Applications

1.4.1 Applications

With power management, the controller can handle simple or advanced applications for a variety of power plant projects. Applications include synchronising generators, critical power, emergency standby, and power production.

CAN bus based power management:

- 32 prime movers and generators (gensets)/mains with breakers.
- 8 bus tie breakers on the generator bus or load bus.
- 16 automatic sustainable controllers. *

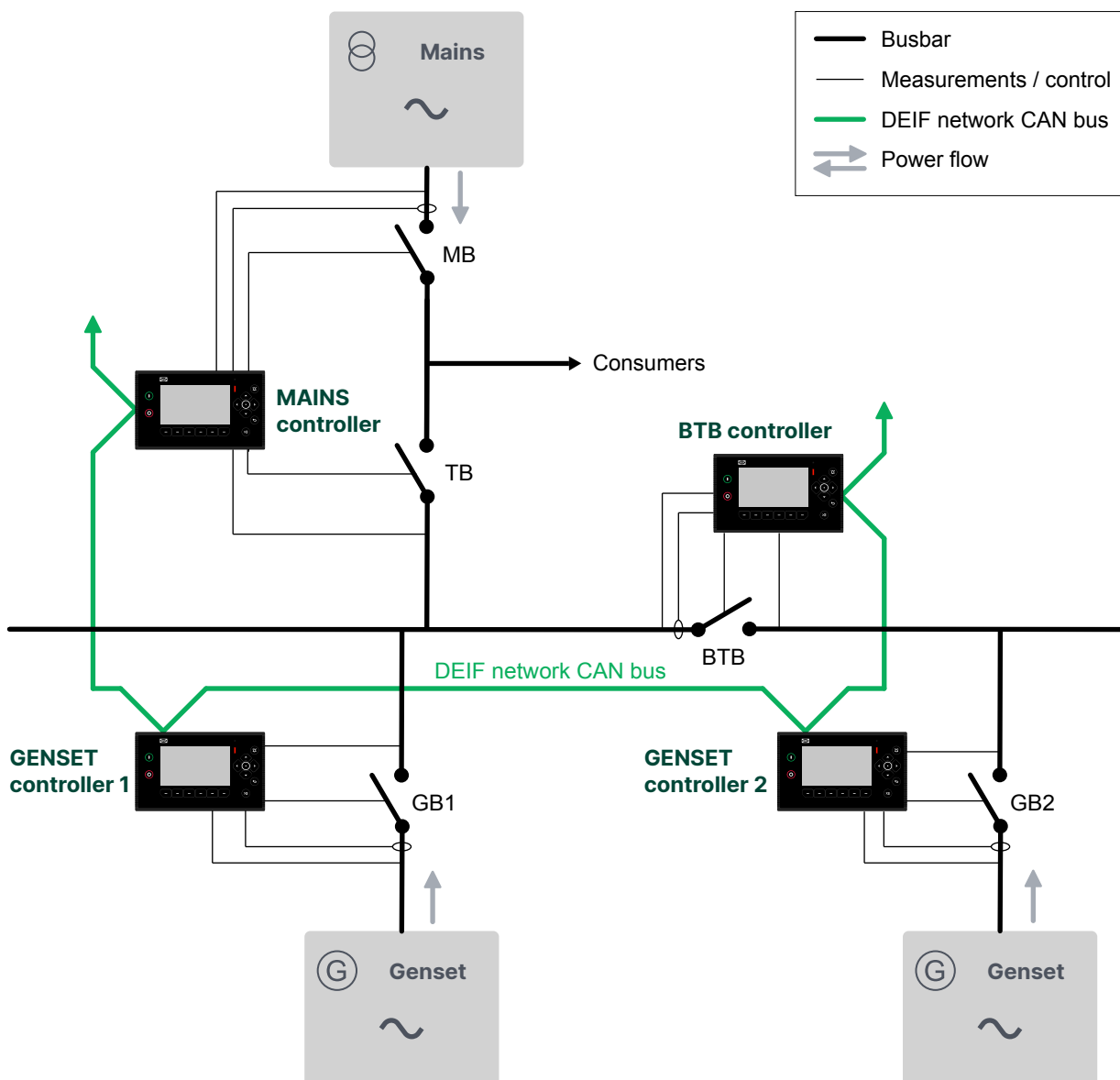
Ethernet based power management: *

- Up to 1000 units on one busbar. *

NOTE * Contact DEIF for availability.

The complete power management system is easily monitored and controlled from PICUS through a graphical supervision page. The values that are presented in the intuitive and easy-to-use user interface include the running status, hours in operation, breaker status, condition of mains and busbars, and fuel consumption.

Example application



1.5 Compatible products

1.5.1 Power management

You can use iE 250 controllers together in a power management system:

- **AGC 150 Generator** (see www.deif.com/products/agc-150-generator)
- **AGC 150 Mains** (see www.deif.com/products/agc-150-mains)
- **AGC 150 BTB** (see www.deif.com/products/agc-150-btb)
- **AGC-4 Mk II Genset, Mains, BTB, Group, and Plant** (see www.deif.com/products/agc-4-mk-ii)
- **AGC-4 Genset, Mains, BTB, Group, and Plant** (see www.deif.com/products/agc-4)

- **ASC 150 Storage** (see www.deif.com/products/asc-150-storage) *
- **ASC 150 Solar** (see www.deif.com/products/asc-150-solar/) *
- **ASC-4 Solar** (see www.deif.com/products/asc-4-solar) *
- **ASC-4 Battery** (see www.deif.com/products/asc-4-battery) *

NOTE * Contact DEIF for availability.

1.5.2 DEIF digital voltage controllers (DVC)

DVC 350 is a digital AVR designed for alternators with SHUNT, AREP or PMG excitation. The DVC 350 monitors and regulates the alternator output voltage. iE 250 can control the DVC 350 features and receive fault information directly with the CAN bus communication.



More information

See www.deif.com/products/dvc-350

DVC 550 is an advanced digital AVR designed for alternators with SHUNT, AREP or PMG excitation. The DVC 550 monitors and regulates the alternator output voltage. iE 250 can control all the DVC 550 features and receive fault information directly with the CAN bus communication.



More information

See www.deif.com/products/dvc-550

1.5.3 Additional inputs and outputs

ML 300 extension modules

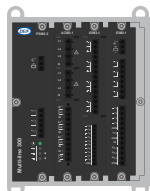
You can use the Multi-line 300 (ML 300) extensions racks and range of modules.



More information

See www.deif.com/products/multi-line-300-modules/ for information about all the racks and modules.

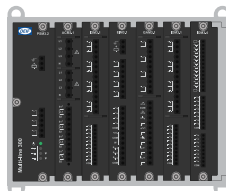
Extension racks



Extension rack R4.1

1 PSM3.2

3 module selection



Extension rack R7.1

1 PSM3.2

6 module selection

Modules



IOM3.1 - Input/output module

4 changeover relay outputs

10 digital inputs



IOM3.2 - Input/output module

4 relay outputs

4 analogue multifunctional outputs (including 2 pulse width modulation PWM outputs)

4 digital inputs

4 analogue multifunctional inputs



IOM3.3 - Input/output module

10 analogue multifunctional inputs



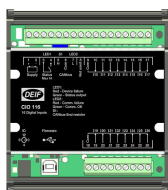
IOM3.4 - Input/output module

12 digital outputs

16 digital inputs

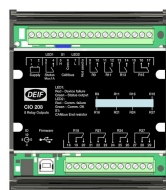
CAN bus Input Output modules (CIO) *

You can use the complete range of CIO modules.



CIO 116

16 digital inputs



CIO 208

8 relay outputs



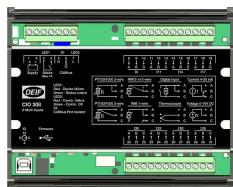
More information

See www.deif.com/products/cio-116



More information

See www.deif.com/products/cio-208



CIO 308

8 multifunctional inputs



More information

See www.deif.com/products/cio-308

NOTE * Contact DEIF for availability.

1.5.4 Remote monitoring service: Insight

Insight is a responsive remote monitoring service. It includes real-time genset data, a customisable dashboard, GPS tracking, equipment and user management, email and/or SMS alerts, and cloud data management.



More information

See www.deif.com/products/insight

1.5.5 Other equipment

DEIF has a wide variety of other equipment that is compatible. This includes synchroscopes, meters, transducers, current transformers, power supplies, and battery chargers.



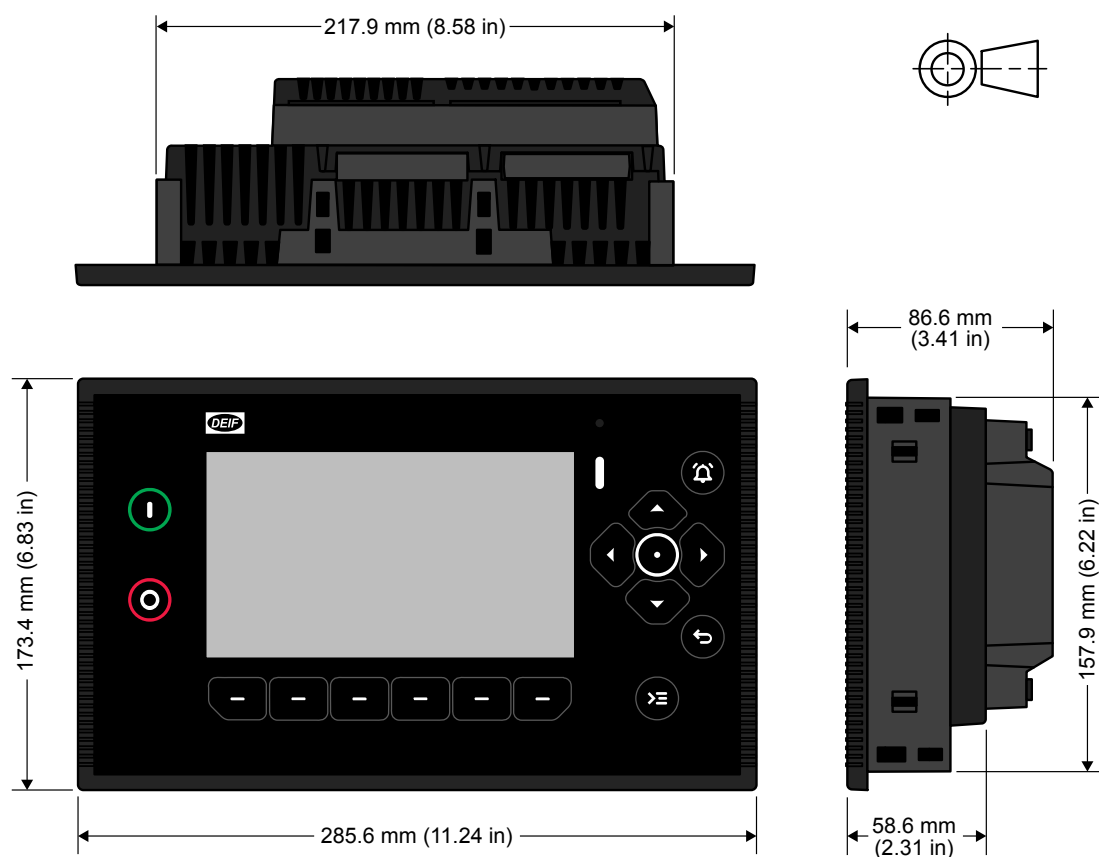
More information

See www.deif.com

2. Technical specifications

2.1 Dimensions

2.1.1 Front mounted controller with MIO2.1



Category	Specifications
Dimensions	With MIO: L×H×D: 285.6 × 173.4 × 86.6 mm (11.24 × 6.83 × 3.41 in) (outer frame)
	Without MIO: L×H×D: 285.6 × 173.4 × 58.6 mm (11.24 × 6.83 × 2.30 in) (outer frame)
Panel cutout	L×H: 218.5 × 158.5 mm (8.60 × 6.24 in) Tolerance: ± 0.3 mm (0.01 in)
Weight	With MIO: ~ 1233 g (2.72 lb)

2.2 Mechanical specifications

2.2.1 Front mounted controller with MIO2.1

Mechanical specifications	
Vibration	<p>Response:</p> <ul style="list-style-type: none"> 10 to 58.1 Hz, 0.15 mmpp 58.1 to 150 Hz, 1 g. To IEC 60255-21-1 (Class 2) <p>Endurance:</p> <ul style="list-style-type: none"> 10 to 150 Hz, 2 g. To IEC 60255-21-1 (Class 2) <p>Seismic vibration:</p> <ul style="list-style-type: none"> 3 to 8.15 Hz, 15 mmpp 8.15 to 35 Hz, 2 g. To IEC 60255-21-3 (Class 2)
Shock	<p>10 g, 11 ms, half sine. To IEC 60255-21-2 Response (Class 2)</p> <p>30 g, 11 ms, half sine. To IEC 60255-21-2 Withstand (Class 2)</p> <p>50 g, 11 ms, half sine. To IEC 60068-2-27, test Ea</p> <p>Tested with three impacts in each direction in three axes (total of 18 impacts per test)</p>
Bump	<p>20 g, 16 ms, half sine IEC 60255-21-2 (Class 2)</p> <p>Tested with 1000 impacts in each direction on three axes (total of 6000 impacts per test)</p>
Controller galvanic separation	<p>Supply and DIO 1 to 8: 550 V, 50 Hz, 1 minute</p> <p>AIO 1 to 4: 550 V, 50 Hz, 1 minute</p> <p>COM 1 (RS-485): 550 V, 50 Hz, 1 minute</p> <p>COM 2 (RS-485): 550 V, 50 Hz, 1 minute</p> <p>CAN A: 550 V, 50 Hz, 1 minute</p> <p>CAN B: 550 V, 50 Hz, 1 minute</p> <p>CAN C: 550 V, 50 Hz, 1 minute</p> <p>Ethernet port 1: 550 V, 50 Hz, 1 minute</p> <p>Ethernet port 2: 550 V, 50 Hz, 1 minute</p> <p>Ethernet port 3: 550 V, 50 Hz, 1 minute</p> <p>Ethernet ETH0 / Ethernet 0 : 550 V, 50 Hz, 1 minute</p>
Controller ports without galvanic separation	Display port, USB port
MIO2.1 galvanic separation	<p>GOV: 550 V, 50 Hz, 1 minute</p> <p>AVR: 3000 V, 50 Hz, 1 minute</p> <p>AC current via internal transformers (I4, I1, I2, I3): 2210 V, 50 Hz, 1 minute</p> <p>AC voltage A-side (N, L1, L2, L3): 3310 V, 50 Hz, 1 minute</p> <p>AC voltage B-side (N, L1, L2, L3): 3310 V, 50 Hz, 1 minute</p> <p>EtherCAT port: 550 V, 50 Hz, 1 minute</p>
MIO2.1 terminals without galvanic separation	D+ and DIO 9 to 16, DI 1 to 8 and tachometer
Safety	<p>Installation CAT. III 600 V</p> <p>Pollution degree 2</p> <p>IEC 60255-27</p>
Flammability	All plastic parts are self-extinguishing to UL94-V0
EMC	IEC 60255-26

NOTE g = gravitational force (g-force).

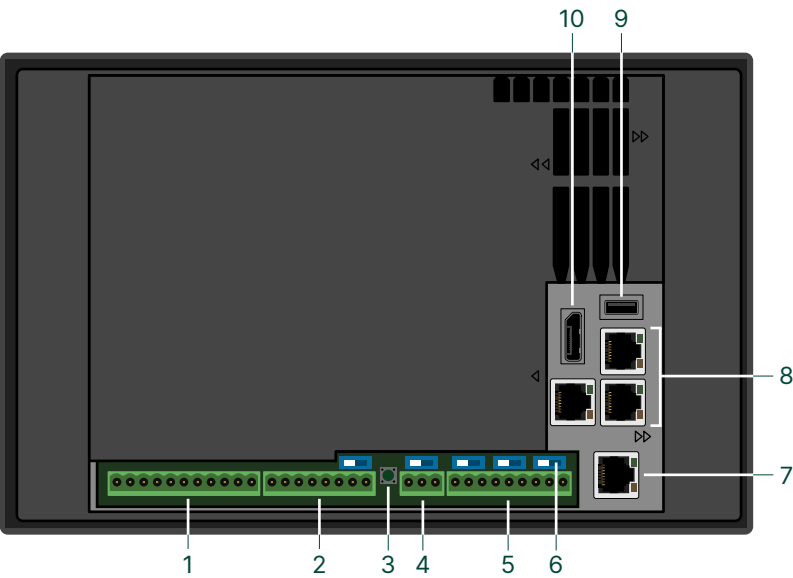
2.3 Environmental specifications

2.3.1 Front mounted controller with MIO2.1

Environmental specifications	
Operating temperature	-30 to 70 °C (-22 to 158 °F)
Storage temperature	-30 to 80 °C (-22 to 176 °F)
Change of temperature	70 to -30 °C, 1 °C / minute, 5 cycles. To IEC 60255-1
Operating altitude	0 to 4000 m above sea level 2001 to 4000 m: Maximum 480 V AC
Operating humidity	Damp heat cyclic, Condensing. Low temperature: 25°C / 97%RH, high temperature: 55°C / 93%RH, for 144 hours. To EN /IEC 60255-1. Damp heat steady state, Non-Condensing. 40°C / 93%RH, for 240 hours. To EN /IEC 60255-1.
Protection degree	EN IEC 60529 <ul style="list-style-type: none">• IP65 (front of module when installed into the control panel with the supplied sealing gasket)• IP20 on terminal side

2.4 Controller

2.4.1 Terminal connections



No.	Function	Notes
1	Power supply Digital bi-directional channels *	1 Power supply (DC+/-) 8 Bi-directional digital channels * DC(+) for DIO 4 to 8
2	COM 1 ** Analogue bi-directional channels	1 RS-282/RS-485 ** 4 Bi-directional analogue channels
3	Push-button **	
4	COM 2 **	1 RS-485 **
5	CAN	3 CAN connections
6	Built-in end resistors	5 switches to enable the end resistors 120 Ω (Ohm) for CAN or Serial termination
7	ETH0 / Ethernet 0	1 Ethernet connection bridged to switch
8	Ethernet	3 Ethernet switch connections
9	USB **	USB host (type A)
10	DisplayPort ***	For use with the base-mounted version ***

NOTE * Breaker functions must be assigned to MIO channels.
 ** Future use. Can be used with CODESYS if license is installed.
 *** Contact DEIF for availability.

2.4.2 Electrical specifications

Power supply	
Input voltage	Nominal voltage: 12 V DC or 24 V DC (Operation range: 6.5 to 36 V DC) Power up at 8 V Operation down to 6.5 V at 15 W Operation down to 6.9 V at 28 W
Start current	Power supply current limiter

Power supply	
	<ul style="list-style-type: none"> • 24 V: 4 A minimum • 12 V: 8 A minimum Battery: No limit
Voltage withstand	Reverse polarity
Power supply drop-out immunity	0 V DC for 50 ms (coming from more than 6.5 V DC) at 15 W
Power supply load dump protection	Load dump protected according to ISO16750-2 test A
Power consumption	15 W typical 28 W maximum

Battery voltage measurement	
Accuracy	±0.8 V within 8 to 32 V DC, ±0.5 V within 8 to 32 V DC @ 20 °C

Analogue bi-directional channels	
4 individual channels (isolated group) with configurable function. Configurable as input or output channels. Galvanic separation to CPU All channels in one electric group	
Input channels	
Digital input	0 to 24 V DC with common threshold 4 V
Resistor measurement	Range: 0 to 1 MΩ Accuracy 0 to 80 Ω: ±1 % ±0.5 Ω 80 Ω to 10 kΩ: ±0.4 % 10 to 20 kΩ: ±0.5 % 20 to 200 kΩ: ±1.5 % 200 to 1000 kΩ: ±12 %
Voltage input	0 to +10 V DC (16-bit sigma delta) Accuracy: 0.5 % of full scale over the operating temperature range.
Current input	0 to 20 mA (16-bit sigma delta) Accuracy: 0.6 % of full scale over the operating temperature range.
Output channels	
Voltage output	0 to +10 V DC (13-bit resolution) Accuracy: 0.5 % of full scale over the operating temperature range.
Current output	0 to 20 mA (13-bit resolution) Accuracy: 0.6 % of full scale over the operating temperature range. Maximum 2 channels can be selected as current output (internal power limitation)

Digital bi-directional channels	
8 individual channels (one galvanic isolated group) with configurable function. Negative switching. Configurable as input or output channels.	
Digital input channels	0 to 24 V DC Current source (contact cleaning) Initial 10 mA, continuous 2 mA Negative switching.
Digital output channels	Output voltage: 12 to 24 V DC High side output switch output voltage is dependant on DC+

Digital bi-directional channels	
	<ul style="list-style-type: none"> DIO channels 1 to 4 use terminal 1. DIO channels 5 to 8 use terminal 7. <p>2 A DC inrush and 0.5 A continuous (maximum 2 A for continuous for all channels)</p>

Real-Time Clock (RTC) battery	
Battery type	CR2430 3V battery, rated for operation at -40 to 85°C (-40 to 185 °F). This is not a standard CR2430 battery.

2.4.3 Communication specifications

Communication specifications	
CAN A	Engine, DVC, or power management (isolated)
CAN B	Data connection 2-wire and common (isolated)
CAN C	Switch 120 Ω (ohm) termination resistors
COM 1 (RS-485) *	Data connection 2-wire and common (isolated) 9600 to 115200 baud Switch 120 Ω (ohm) termination resistors
COM 2 (RS-485) *	Data connection 2-wire and common (isolated) 9600 to 115200 baud Switch 120 Ω (ohm) termination resistors
USB *	USB host (type A)
3 Ethernet *	Switch for Ethernet connections RJ45 Use an Ethernet cable that meets or exceeds the SF/UTP CAT5e specifications
ETH0 / Ethernet 0	Ethernet bridged to the switch RJ45 Use an Ethernet cable that meets or exceeds the SF/UTP CAT5e specifications
DisplayPort **	For base-mounted versions only Connection to a local display

NOTE * For future use. Can be used with CODESYS if license is installed.

** Contact DEIF for availability.

2.5 Measurement Input Output module (MIO2.1)

2.5.1 About

The Measurement Input and Output module (MIO2.1) is an add-on module for the iE 250. It features 8 bi-directional digital terminals, allowing smart flexibility where you can use them for what you need.

AC measurements

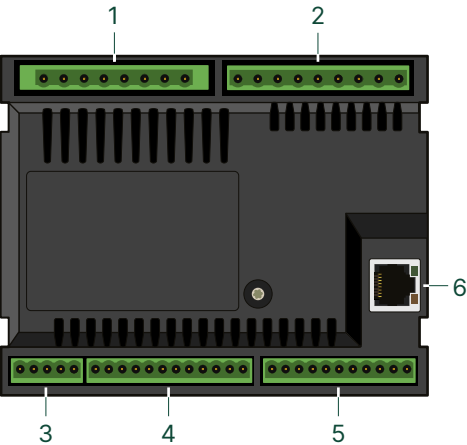
The module measures the voltage and current on one side of a breaker, and the voltage on the other side. The hardware module responds when the measurements exceed the AC alarm parameters.

The module provides robust frequency detection in environments with electrical noise. It allows extended measurement bandwidth up to 40 times the nominal frequency. It includes a configurable 4th current measurement.

Additional features

- Analogue outputs for GOV and AVR.
- 8 Digital input channels.
- Analogue Tacho (MPU/N/NPN/PNP) input.

2.5.2 Terminal connections



No.	Function	Notes
1	AC current via CTs	A-side: L1 (S1,S2) L2 (S1,S2) L3 (S1,S2) A-side or B-side: L4 (S1,S2)
2	AC voltage	A-side: N, L1, L2, L3 B-side: N, L1, L2, L3
3	Analogue output (GOV/AVR)	AVR (+/-) GOV (+/-)
4	D+ and Digital bi-directional channels	D+ Emergency stop (E stop) input 8 Bi-directional configurable channels
5	Digital input channels and Tacho	8 Digital inputs Tacho
6	EtherCAT	Connection to extension racks

2.5.3 Electrical specifications

All AC measurement specifications are within the reference conditions, unless otherwise stated.

Voltage measurements	
Nominal value (Un)	100 to 690 V AC
Reference range	30 to 931.5 V AC
Measurement range	5.0 to 931.5 V AC, Truncation: 2 V AC
Accuracy	5.0 to 931.5 V AC: $\pm 0.5\%$ or ± 0.5 V AC (whichever is greater)
UL/cUL Listed	600 V AC phase-phase
Consumption	Maximum 0.25 VA/phase
Voltage withstand	Un + 35 % continuously Un + 45 % for 10 seconds

Current measurements	
Nominal value (IN)	1 or 5 A AC from current transformer
Measurement range	0.005 to 20.0 A AC, Truncation: 4 mA AC
Accuracy	0.005 to 20.0 A AC: $\pm 0.5\%$ or ± 5 mA AC (whichever is greater)
UL/cUL Listed	From listed or R/C (XODW2.8) current transformers 1 or 5 A AC
Consumption	Maximum 0.3 VA/phase
Current withstand	10 A AC continuous 20 A AC for 1 minute 75 A AC for 10 seconds 250 A AC for 1 second

Frequency measurements	
Nominal value	50 Hz or 60 Hz
Reference range	45 to 66 Hz
Measurement range	10 to 75 Hz
System frequencies	Accuracy: 10 to 75 Hz ± 5 mHz, within the temperature operating range.
Phase frequencies	Accuracy: 10 to 75 Hz ± 10 mHz, within the temperature operating range.

Phase angle (voltage) measurement	
Measurement range	-179.9 to 180°
Accuracy	-179.9 to 180°: 0.2°, within the temperature operating range

Power measurement	
Accuracy	$\pm 0.5\%$ of measured value or $\pm 0.5\%$ of $U_n \cdot I_n$, whichever is greater, within the current measurement range

AC Measurement temperature and accuracy	
AC Measurement reference range	-20 to 55 °C (-4 to 131 °F)
Temperature-dependent accuracy outside the reference range	Voltage: Additional: $\pm 0.05\%$, or ± 0.05 V AC per 10 °C (18 °F) (whichever is greater)

AC Measurement temperature and accuracy

Current: Additional: $\pm 0.05\%$, or ± 0.5 mA AC per $10\text{ }^{\circ}\text{C}$ ($18\text{ }^{\circ}\text{F}$) (whichever is greater)
Power: Additional: $\pm 0.05\%$, or $\pm 0.05\%$ of $U_n \cdot I_N$ per $10\text{ }^{\circ}\text{C}$ ($18\text{ }^{\circ}\text{F}$) (whichever is greater)

Digital input channels

8 individual input channels with configurable function.
Negative switching.
Current source (contact cleaning) Initial 10 mA, continuous 2 mA.

D+

Excitation current	210 mA, 12 V
	105 mA, 24 V
Charging fail threshold	6 V

Tacho

Voltage input range	± 1 to 70 Vp
W	8 to 36 V
Frequency input range	10 to 10 kHz
Frequency measurement tolerance	1 % of reading
Wire break detection	Yes

Digital bi-directional channels

8 bi-directional digital channels with configurable function.
All channels in one electric group.
Configurable as input or output channels.

Digital input	0 to 24 V DC Negative switching Current source (contact cleaning) Initial 10 mA, continuous 2 mA
Digital output	Supply voltage: 12 to 24V (operating range 6.5 to 28 V DC) <ul style="list-style-type: none">DIO channels 9 to 12 supply on terminal 46 DC (+) E. stopDIO channels 13 to 16 supply on terminal 52 Output current: Up to 0.5 A (maximum 1 A for each group of 4 channels) 2 A DC inrush and 0.5 A continuous (maximum 2 A for continuous for all channels)

Analogue output for GOV or AVR

Output types for GOV or AVR	DC output or PWM
Minimum load resistance	500 Ω (Ohm) or 20 mA

Governor (GOV)

DC voltage output range	-10.5 to +10.5 V DC
CODESYS controllable *	-10.5 to +10.5 V DC
PWM output voltage	Default 6 V, configurable in platform level via EtherCAT in the range 1 to 10.5 V Application level fixed to platform configuration

Governor (GOV)	
PWM frequency range	1 to 2500 Hz \pm 25 Hz
PWM duty cycle resolution	12 bits (4096 steps)
Accuracy	Accuracy: \pm 1 % of setting

Automatic voltage regulator (AVR)	
DC voltage output range	-10.5 to +10.5 V DC
CODESYS controllable *	-10.5 to +10.5 V
PWM output voltage	Default 6 V, configurable in platform level via EtherCAT in the range 1 to 10.5 V Application level fixed to platform configuration
PWM frequency range	1 to 2500 Hz \pm 25 Hz
PWM duty cycle resolution	12 bits (4096 steps)
Accuracy	Accuracy: \pm 1 % of setting

NOTE * Only configurable for the iE 250 PLC.

2.5.4 Communication specifications

EtherCAT	
EtherCAT communication	RJ45 Use an Ethernet cable that meets or exceeds the SF/UTP CAT5e specifications

2.6 Accessories (optional)

2.6.1 Ethernet cable

The Ethernet cable from DEIF meets the technical specifications below.

Category	Specification
Cable type	Shielded patch cable SF/UTP CAT5e
Temperature	Fixed installation: -40 to 80 °C (-40 to 176 °F) Flexible installation: -20 to 80 °C (-4 to 176 °F)
Minimum bending radius (recommended)	Fixed installation: 25.6 mm (1.01 in) Flexible installation: 51.2 mm (2.02 in)
Length	2 m (6.6 ft)
Weight	~110 g (4 oz)

2.7 Approvals

Standards
CE
UL/cUL Listed to UL/ULC6200:2019, 1. ed. controls for stationary engine gensets



More information

For the most recent approvals and certificates, refer to www.deif.com.

2.8 Cybersecurity

Category	Specification
Cybersecurity	Conforming to IEC 62443 - Level 1 *

NOTE * Connections to untrusted networks may require additional equipment or security counter-measures not included in the product.

3. Legal information

3.1 Disclaimer and copyright

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